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Roll No.

SIXTH SEMESTER

B.Tech (Engineering Physics).

MID SEMESTER EXAMINATION

March, 2019

EP 314 Instrumentation & Control

Time: 1:30 Hours

Max. Marks: 25

Note: Answer all four questions.

Assume suitable missing data, if any.

1. (a) A single input single output system with y as output and x as input, is describe by

$$d^2y/dt^2 + 2dy/dt + 10y = 5dx/dt - 3x$$

For an input x(t) with zero initial conditions the above system produces the same output as with no input and with initial conditions $dy(0^-)/dt = -4$ and $y(0^-) = 1$, find x(t).

(b) A linear network has the system function

$$T(s) = K(s+c)/(s+a)(s+b)$$

The outputs of the network with zero initial conditions for two different inputs are tabled as

Input x(t)	Output y(t)
u(t)	2+De ^{-t} + Ee ^{-3t}
e ^{-2t} u(t)	Fe ^{-t} + Ge ^{-3t}

Then find the values of c and K.

3.5

2. (a) Construct the signal flow graph for the following set of simultaneous equations and find the transfer function of the system using Mason's gain formula.

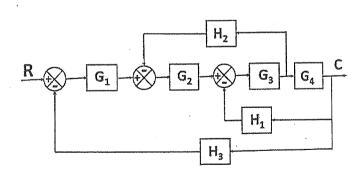
$$x_2=ax_1+bx_3$$
;

$$x_3 = cx_1 + dx_2 + ex_3$$
;

$$x_4=fx_2+gx_3$$

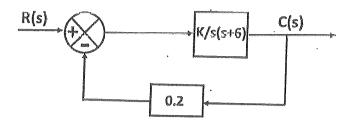
(b) Find C/R using block diagram reduction technique:

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P.T.O

3. (a) A closed loop control system is shown in figure below. The system is having a damping ratio of 0.7. Determine the value of K to satisfy this condition and calculate the setting time, peak time and maximum overshoot for that value of K.



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- (b) A second order control system is represented by a transfer function given as $\theta_0(s)/T(s) = 1/(Js^2+fs+K)$ Where θ_0 is O/p and T is i/p. A step input of 10 Nm is applied to the system and test results are as (a) $M_p=6\%$ (b) $t_p=1$ sec. and (c) the steady state value of the output is 0.5 radian. Determine the value of J, f and K.
- 4. (a) Find the sensitivity S^{T}_{K} of the transfer function T = (1+2K)/(3+4K) with respect to the parameter K.
 - (b) The closed loop transfer function of a unity feedback control system is given by:

$$C(s)/R(s) = (Ks+b)/(s^2+as+b)$$

Determine the steady state error for unit ramp input.