

## TABLE OF CONTENTS

<b>CERTIFICATE .....</b>	<b>ii</b>
<b>ACKNOWLEDGEMENT .....</b>	<b>iii</b>
<b>ABSTRACT .....</b>	<b>iv</b>
<b>CHAPTER-1 INTRODUCTION.....</b>	<b>10</b>
1.1 OVERVIEW .....	10
1.2 FEATURE SELECTION FOR TRACKING.....	10
1.2 ISSUES IN OBJECT TRACKING .....	11
1.4 PROBLEM STATEMENT .....	13
1.5 THESIS LAYOUT .....	14
<b>CHAPTER-2 LITERATURE REVIEW.....</b>	<b>16</b>
2.1 OVERVIEW .....	16
2.2 LITERATURE SURVEY .....	16
<b>CHAPTER-3 BASIC CONCEPTS.....</b>	<b>22</b>
3.1 OVERVIEW .....	22
3.2 GRAPH CUTS.....	22
3.2.1 <i>Definition</i> .....	23
3.2.2 <i>Capacity and Flow</i> .....	23
3.2.3 <i>Minimum Cut</i> .....	24
3.2.4 <i>Maximum Cut</i> .....	25
3.2.5 <i>Max-Flow Min-Cut Theorem</i> .....	25
3.3 GRAPH CUTS IN COMPUTER VISION.....	26
3.4 GRAPH CUT SEGMENTATION .....	26
3.4.1 <i>Graph Construction</i> .....	26
3.4.2 <i>Segmentation Energy</i> .....	27
3.4.3 <i>Segmentation</i> .....	28
3.5 BACKGROUND SUBTRACTION .....	28
3.6 KALMAN FILTERING .....	30
3.6.1 <i>Basics of Kalman Filter</i> .....	31

3.6.2 <i>Kalman Filter for Multiple Object Tracking</i> .....	32
<b>CHAPTER 4 PRESENTED METHOD</b> .....	<b>34</b>
4.1 OVERVIEW .....	34
4.2 PRESENTED METHOD.....	34
4.3 FLOW DIAGRAM .....	35
4.4 IMPLEMENTATION STEPS .....	36
<b>CHAPTER 5 RESULTS AND DISCUSSION</b> .....	<b>37</b>
5.1 RESULTS .....	37
5.1.1 <i>Graph Cut Segmentation Results</i> .....	37
5.1.2 <i>Tracking Results</i> .....	43
5.2 DISCUSSION .....	48
<b>CHAPTER 6 CONCLUSION AND FUTURE SCOPE</b> .....	<b>49</b>
5.1 CONCLUSION .....	49
5.2 SCOPE OF FUTURE WORK.....	49
<b>REFERENCES</b> .....	<b>51</b>
<b>APPENDIX A</b> .....	<b>54</b>

## LIST OF FIGURES

3.1 Example of a directed capacitated graph.....	22
3.2 Illustration of capacity of a cut.....	23
3.3 Illustration of flow.....	24
3.4 Flow Assignment.....	24
3.5 Max-Flow Min-Cut Theorem.....	25
3.6 A simple 2D segmentation example of 3X3 image.....	27
3.7 Flow chart of background subtraction.....	29
3.8 Flow chart of Kalman filter.....	30
4.1 Flow chart of presented method.....	35
5.1 Segmented Video Frames of Test Video 1 (2 Frames).....	37
5.2 Segmented Video Frames of Test Video 1 (Next 10 Frames).....	38
5.3 Segmented Video Frames of Test Video 1 (Next 10 Frames).....	39
5.4 Segmented Video Frames of Test Video 2 (Last 2 Frames).....	40
5.5 Segmented Video Frames of Test Video 2 (6 Frames).....	40
5.6 Segmented Video Frames of Test Video 2 (Last 6 Frames).....	41
5.7 Segmented Video Frames of Test Video 3 (4 Frames).....	41
5.8 Segmented Video Frames of Test Video 3 (Next 10 Frames).....	42
5.9 Segmented Video Frames of Test Video 3 (Last 2 Frames).....	43
5.10 Tracking Results on Test Video 1 (4 Frames).....	44

5.11 Tracking Results on Test Video 1 (Next 10 Frames).....	45
5.12 Tracking Results on Test Video 2.....	45
5.13 Tracking Results on Test Video 3 (10 Frames).....	46
5.14 Tracking Results on Test Video 3 (Last 10 Frames).....	47
A.1 Original video frames of test video1.....	54
A.2 Original video frames of test video2.....	55
A.3 Original video frames of test video3 (16 Frames).....	55
A.4 Original video frames of test video3 (Last 18 Frames).....	56

## LIST OF ABBREVIATIONS

HOG	Histogram of Oriented Gradients
BoF	Bag of Features
SIFT	Scale Invariant Feature Transform
GMM	Gaussian Mixture Model
GNN	General Nearest Neighbor
LBP	Local Binary Pattern
SSE	Sum of Squared Errors
PCA	Principal Component Analysis
MOT	Multi-Object Tracking
HCI	Human Computer Interaction
MRF	Markov Random Field
Min Cut	Minimum Cut
Max Flow	Maximum Flow
MATLAB	Matrix Laboratory
RDHOGPF	Relative Discriminative Histogram-of-Oriented-Gradients Based Particle Filter